

# Heteroscedastic PCA (HPCA)

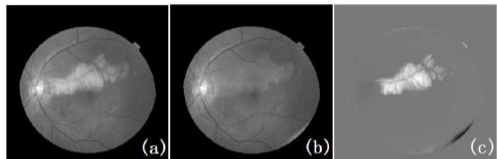
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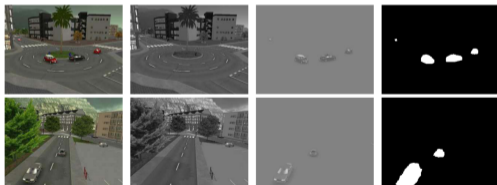
University of Michigan

January, 2023

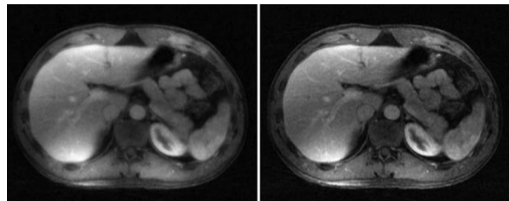
# Applications



Lesion Detection [1]



Motion Estimation [3]



Dynamic MRI Reconstruction [2]

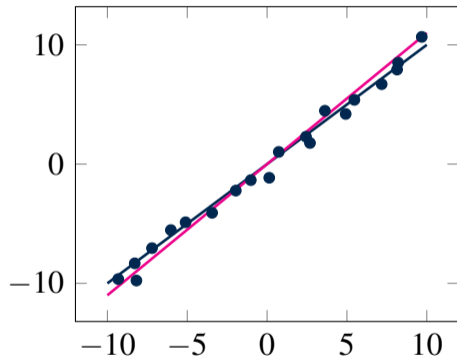


Image/Video Denoising [4]

# Heteroscedasticity

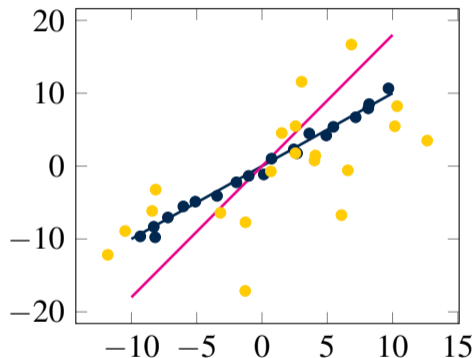
Homoscedastic Data

$$y_i = x_i + \epsilon \text{ s.t. } \epsilon \sim \mathcal{N}(\mathbf{0}, \nu I)$$



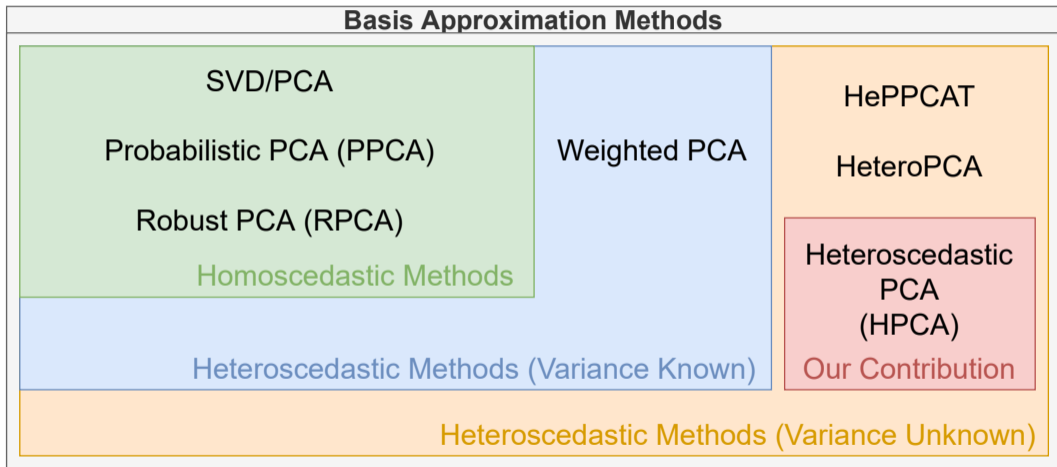
Heteroscedastic Data

$$y_i = x_i + \epsilon_i \text{ s.t. } \epsilon_i \sim \mathcal{N}(\mathbf{0}, \nu_i I)$$



$x_i = U z_i$  where  $\hat{U}$  = estimated subspace basis,  $z_i$  = basis coordinates

# Background



# Robust PCA (RPCA)

## Key Idea

Robust PCA = PCA + Outlier Robustness

Let  $Y = [\mathbf{y}_1, \dots, \mathbf{y}_n] \in \mathbb{R}^{D \times N}$  be a data matrix

Decompose  $Y$  such that  $\underbrace{Y}_{\text{data matrix}} = \underbrace{L}_{\text{low rank data}} + \underbrace{S}_{\text{outlier matrix}}$

Solve the following optimization problem:

$$\arg \min_{L, S} \underbrace{\lambda_r \|L\|_*}_{\text{low rank}} + \underbrace{\|S\|_{1,1}}_{\text{outliers}} \quad \text{s.t. } Y = L + S \quad \text{where } \|L\|_* = \sum_{i=1}^{\min(M,N)} \sigma_i(L)$$

# Model Limitations

$$\text{RPCA: } \arg \min_{L,S} \underbrace{\lambda_r \|L\|_*}_{\text{low rank}} + \underbrace{\|S\|_{1,1}}_{\text{outliers}} \quad \text{s.t. } Y = L + S \quad \text{where } \|L\|_* = \sum_{i=1}^{\min(M,N)} \sigma_i(L)$$

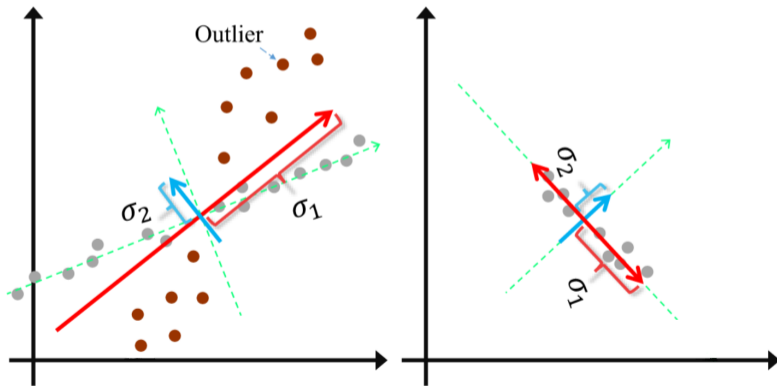


Image Courtesy: Oh et. al. [5]

# Heteroscedastic PCA (HPCA)

## Key Idea

HPCA = Robust PCA (RPCA) + Heteroscedastic Noise

Let  $Y = [\mathbf{y}_1, \dots, \mathbf{y}_n] \in \mathbb{R}^{D \times N}$  and  $\Pi = \text{diagm}(\nu_1, \dots, \nu_n) \in \mathbb{R}^{N \times N}$

Decompose  $Y$  such that  $\underbrace{Y}_{\text{data matrix}} = \underbrace{X}_{\text{low rank data}} + \underbrace{Z}_{\text{noise matrix}}$

Then the optimization problem we posed is the following:

$$\arg \min_{X, Z, \Pi} \underbrace{\lambda_r \|X\|_{\otimes, \alpha}}_{\text{low rank}} + \underbrace{\frac{1}{2} \|Z\Pi^{-1/2}\|_F^2}_{\text{weighted noise}} + \underbrace{\frac{D}{2} \log \overset{\text{det.}}{|\Pi|}}_{\text{unk. variance}} \quad \text{s.t. } Y = X + Z$$

# Heteroscedastic PCA (HPCA)

Let  $Y = [\mathbf{y}_1, \dots, \mathbf{y}_n] \in \mathbb{R}^{D \times N}$  and  $\Pi = \text{diagm}(\nu_1, \dots, \nu_n) \in \mathbb{R}^{N \times N}$

$$\arg \min_{X, Z, \Pi} \underbrace{\lambda_r \|X\|_{\otimes, \alpha}}_{\text{low rank}} + \underbrace{\frac{1}{2} \|Z\Pi^{-1/2}\|_F^2}_{\text{weighted noise}} + \underbrace{\frac{D}{2} \log \overbrace{|\Pi|}^{\text{det.}}}_{\text{unk. variance}} \quad \text{s.t. } Y = X + Z$$

$$\|X\|_{\otimes, \alpha} \triangleq \sum_{i=\alpha+1}^{\min(M, N)} \sigma_i(X) = \sum_{i=1}^{\min(M, N)} \sigma_i(X) - \sum_{i=1}^{\alpha} \sigma_i(X) = \|X\|_* - \|X\|_{\text{Ky-Fan}(\alpha)}$$

## Note!

$\alpha = 0 \implies \|X\|_{\otimes, \alpha} = \|X\|_*$  (convex assuming known variance)

$\alpha > 0, \lambda_r \rightarrow \infty \implies \hat{X} \implies \text{SVP}(X, \alpha) = U_\alpha \Sigma_\alpha V_\alpha^T$  (nonconvex)



# Experimental Setup

- 1 Define  $W \in \mathbb{R}^{D \times N}$  to be a random Uniform matrix ( $w_{ij} \sim U[0, 1]$ )
- 2 Knowing that  $\text{SVD}(W) = U\Sigma V^T$ , get  $U_\alpha = U[:, 1 : \alpha]$  for known  $\alpha < D$
- 3 Let  $\mathbf{z}_i \sim U[-a, a]$  or  $\mathbf{z}_i \sim \mathcal{N}(0, a^2)$  such that  $\mathbf{x}_i = U_\alpha \mathbf{z}_i \quad \forall i$
- 4 Then,  $\forall i \quad \mathbf{y}_i = \mathbf{x}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \nu_i)$
- 5 Collect all  $\mathbf{y}_i$  such that  $Y = [\mathbf{y}_1, \dots, \mathbf{y}_n]$  and  $\Pi = \text{diagm}(\nu_1, \dots, \nu_n)$
- 6 Run opt. problem to find  $\hat{X}$  and do  $\text{SVD}(\hat{X}) \implies \hat{U}$   
Measure subspace affinity error  $\|U_\alpha U_\alpha' - \hat{U} \hat{U}'\|_F / \|U_\alpha U_\alpha'\|_F$

# Benchmark Comparisons

## Probabilistic PCA (PPCA) [homoscedastic]

- Hard rank constraint, assumes same noise variance

## Robust PCA (RPCA) [homoscedastic]

- RPCA is excluded from results to prevent straw man argument

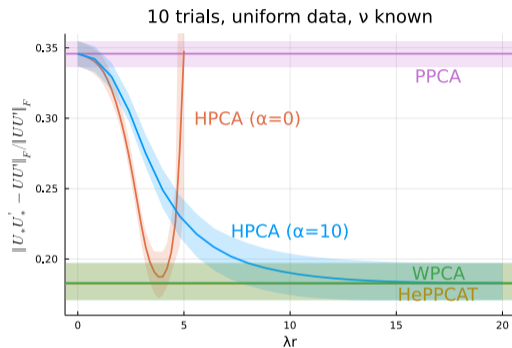
## Weighted PCA (WPCA) [heteroscedastic]

- Weighted sample covariance method
- Hard rank constraint, assumes known variances

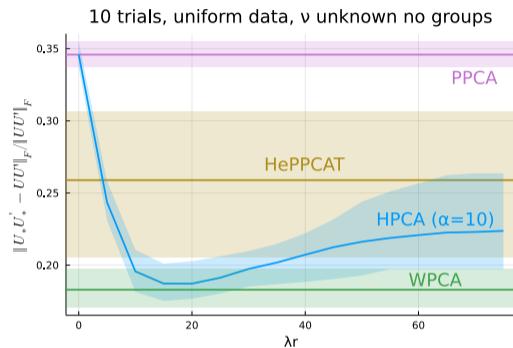
## Heteroscedastic Probabilistic PCA Technique (HePPCAT) [hetero.]

- Factor analysis method
- Hard rank constraint, solves unknown variance case

# Planted Model Results (Sample Heteroscedasticity)



known variance case

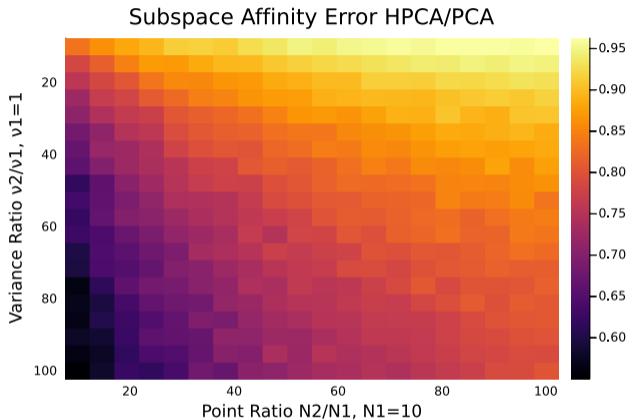


unknown variance case

$\nu_1$	$\nu_2$	Total Points	Ambient Dimension	Subspace Dimension	Good Samples
0.5	10	500	100	10	10

# PCA Comparison

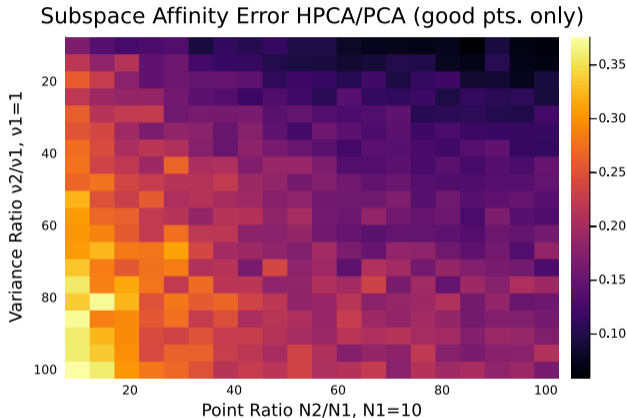
Param.	Value
Subspace Dim.	10
Ambient Dim.	100
Good Samples	10
$\nu_1$	1
Basis Coordinate Range	100
Trials	10



known variance case

# PCA Comparison (HPCA = All Pts., PCA = Good Pts.)

Param.	Value
Subspace Dim.	10
Ambient Dim.	100
Good Samples	10
$\nu_1$	1
Basis Coordinate Range	100
Trials	10



# Algorithm Summary

- handles **both forms** of heteroscedasticity (not shown for brevity)
- no **distributional assumptions** about the low rank data
- **flexible** whether rank is known or not
- **convex** cases when the variances are known
- **extends** to linear operators (not shown for brevity)
- **outperforms** current methods like HeteroPCA and HePPCAT\*

\* at the cost of computation time & learning the regularization parameter

# Future Work I

Fast HPCA (Burer-Monteiro decomposition + balancing preconditioners)

Let  $X = UV^T$  where  $U \in \mathbb{R}^{D \times k}$  and  $V^T \in \mathbb{R}^{k \times N}$  for known rank  $k$

$$\arg \min_{U, V, \Pi} \frac{1}{2} \underbrace{\| [Y - \underbrace{UV^T}_{\text{nonconvex matrix factorization}}] \overbrace{\Pi^{-1/2}}^{\text{weighted noise}} \|_F^2}_{\text{unknown variances}} + \underbrace{\frac{D}{2} \log |\Pi|}_{\text{unknown variances}}$$

$$U_{k+1} = U_k - \alpha \nabla_U f(U_k, V_k, \Pi_k) \underbrace{(V_k^T V_k)^{-1}}_{\text{balancing term}} \quad V_{k+1} = V_k - \alpha \nabla_V f(U_k, V_k, \Pi_k) \underbrace{(U_k^T U_k)^{-1}}_{\text{balancing term}}$$

Idea inspired by Yuejie Chi's work on ScaledGD [6]

# Conclusion

- Heteroscedasticity is problematic for many algorithms
- Noisy data still contains information about the basis
- Robust PCA works for outliers but fails under heteroscedastic cases
- HPCA builds off Robust PCA for heteroscedastic situations
- Future work on fast implementation & Union of Subspaces (UoS)



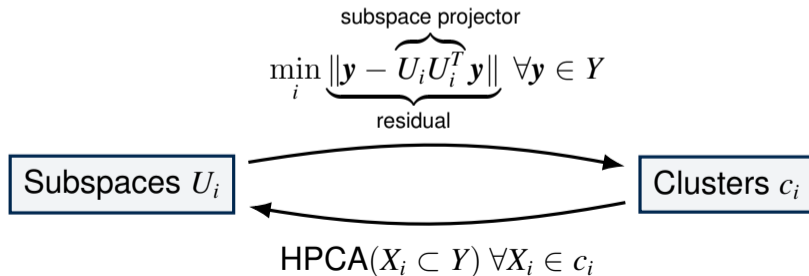
# Scratch Slide

# Future Work II

## Heteroscedastic k-Subspaces

$$\min_{\mathcal{C}, \mathcal{U}} \sum_{k=1}^K \sum_{i: y_i \in c_k} \|y_i - U_k U_k^T y_i\|_2^2$$

$\mathcal{C} = \{c_1, \dots, c_k\}$  = estimated clusters,  $\mathcal{U} = \{U_1, \dots, U_K\}$  = subspace bases



# Benchmark Comparison Algorithms I

## Probabilistic PCA (PPCA)

In factor analysis, the following latent variable model relates observation data  $t$  to unobserved variable  $x$ :

$$t = Wx + \mu + \epsilon, \text{ where } x \sim \mathcal{N}(0, I), \epsilon \sim \mathcal{N}(0, \sigma^2 I), t \sim \mathcal{N}(\mu, \underbrace{WW^T + \sigma^2 I}_C)$$

Then, for sample covariance matrix  $S_t$ , the log-likelihood is:

$$\mathcal{L} = -\frac{N}{2}(d \log(2\pi) + \log(\det(C)) + \text{tr}(C^{-1}S))$$

The subspace basis is found by orthogonalizing  $W$  via SVD

# Benchmark Comparison Algorithms II

## Weighted PCA (WPCA)

Given weights  $w_1, \dots, w_N$  for points  $y_1, \dots, y_N$  form the weighted sample covariance matrix as:

$$S = \sum_{i=1}^N w_i [y_i y_i']$$

and get subspace basis by performing:

$$\hat{U} = [\hat{u}_1, \dots, \hat{u}_k] = \text{EVD}(S)$$

for given rank  $k$  and weights  $w_i = \frac{1}{\sigma_i^2}$  (a natural choice)

# Benchmark Comparison Algorithms III

## Heteroscedastic Probabilistic PCA Technique (HePPCAT)

For  $n_1 + \dots + n_L = n$  data samples from  $L$  noise groups, the model is described as

$$y_{l,i} = Fz_{l,i} + \epsilon_{l,i} \quad i \in \{1, \dots, n_L\}, l \in \{1, \dots, L\}$$

for scores  $z_{l,i} \sim \mathcal{N}(0, v_l I)$  and points  $y_{l,i} \sim \mathcal{N}(0, FF^T + v_l I)$

Form the log-likelihood as the following:

$$\mathcal{L}(F, v) = \frac{1}{2} \sum_{l=1}^L [n_l \ln \det(FF^T + v_l I)^{-1} - \text{tr}\{Y_l^T (FF^T + v_l I)^{-1} Y_l\}]$$

# Feature HPCA

Let  $Y = [\mathbf{y}_1, \dots, \mathbf{y}_n] \in \mathbb{R}^{D \times N}$  and  $W = \text{diag}(w_1, \dots, w_D) \in \mathbb{R}^{D \times D}$

Consider a model with heteroscedasticity across the features

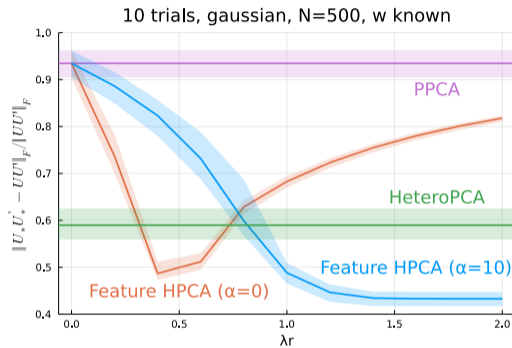
$$\mathbf{y}_i = \mathbf{x}_i + \boldsymbol{\epsilon} \quad \text{s.t.} \quad \underbrace{\boldsymbol{\epsilon} \sim \mathcal{N}(\mathbf{0}, W)}_{\text{same for each point!}}$$

$$\arg \min_{X, Z, W} \underbrace{\lambda_r \|X\|_{\otimes, \alpha}}_{\text{low rank}} + \underbrace{\frac{1}{2} \|W^{-1/2} Z\|_F^2}_{\text{weighted features}} + \underbrace{\frac{D}{2} \log |W|}_{\text{unk. quality}} \quad \text{s.t.} \quad Y = X + Z$$

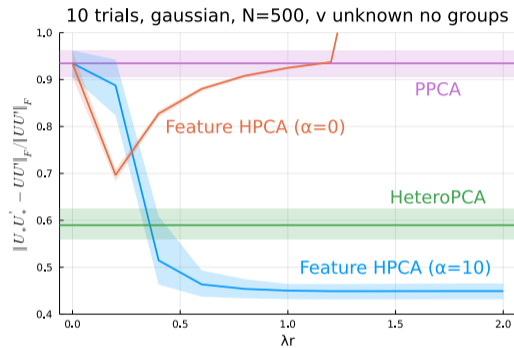
Note!

$W$  updates  $\implies$  using feature space sample covariance matrix

# Planted Model Results (Feature Heteroscedasticity)



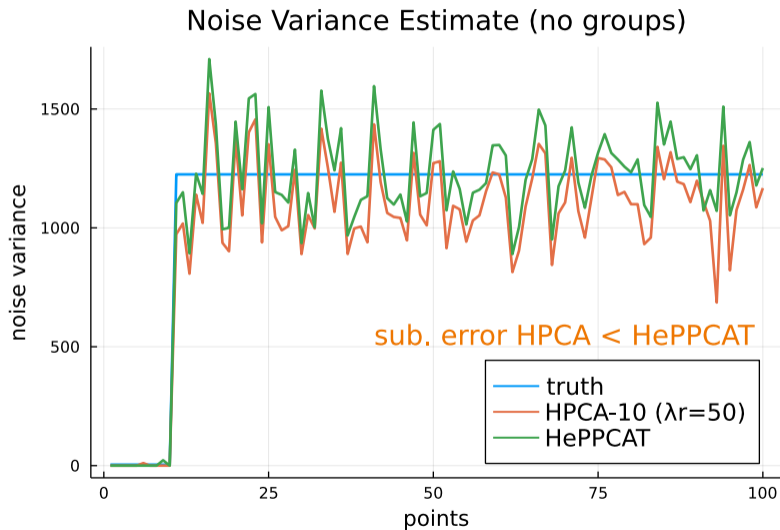
known variance case



unknown variance case

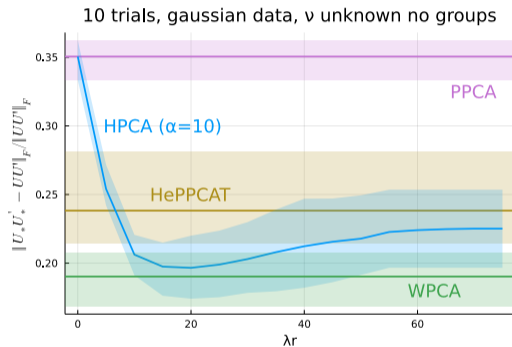
$w_1$	$w_2$	Total Points	Ambient Dimension	Subspace Dimension	Good Features
2	35	500	100	10	50

# HPCA Variance Estimation

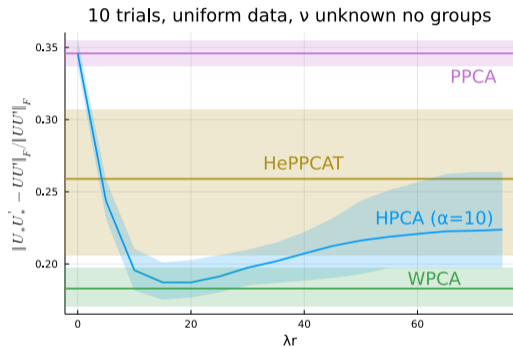




# HPCA/HePPCAT Distribution Effects



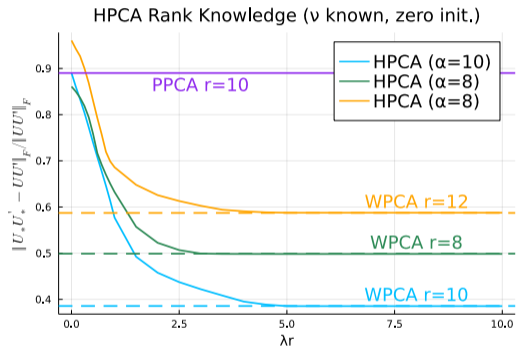
Gaussian case



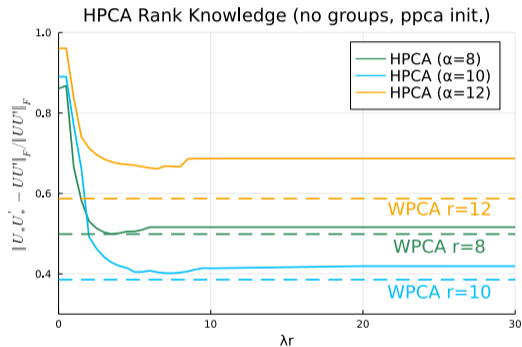
Uniform case

$\nu_1$	$\nu_2$	Total Points	Ambient Dimension	Subspace Dimension	Good Samples
0.5	10	500	100	10	10

# HPCA Rank Knowledge



Known variance case



Unknown variance case

# Low Rank Matrix Completion I

Consider a general linear mapping  $\mathcal{A}(\cdot) : \mathbb{R}^{D \times N} \rightarrow \mathbb{R}^{D \times N}$

$$\arg \min_{X, \Pi} \underbrace{\lambda_r \|X\|_{\otimes, \alpha}}_{\text{low rank}} + \underbrace{\frac{1}{2} \|[Y - \mathcal{A}(X)]\Pi^{-1/2}\|_F^2}_{\text{weighted noise}} + \underbrace{\frac{D}{2} \log |\Pi|}_{\text{unk. variance}}$$

## Examples

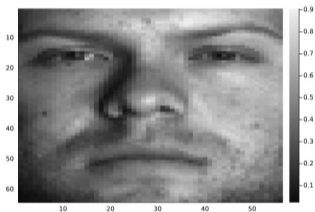
$\mathcal{A}(X) = M \odot X = \tilde{M}X$  (missing data i.e. matrix completion)

$\mathcal{A}(X) = H \circledast X_i \quad \forall i = \tilde{H}X$  (deconvolution e.g. phase retrieval)

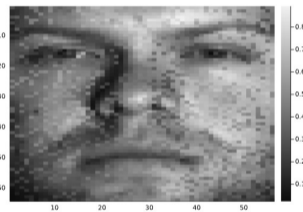
$\mathcal{A}(X) = FX$  (forward models e.g. MRI encoding matrix)

# Low Rank Matrix Completion II

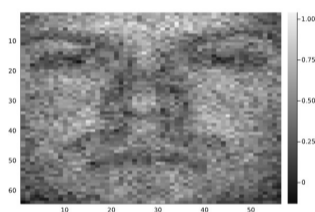
original image



low noise image



high noise image



$\nu_1^{1/2}$	$\nu_2^{1/2}$	Total Samples	Good Samples	Ambient Dimension	Subspace Dimension	Corruption Factor
0.01	0.1	22	1	3584	$\approx 4$	20%

# Low Rank Matrix Completion III

low noise image



WPCA



PSNR: 29.2dB

HPCA



PSNR: 35.3dB

$\nu_1^{1/2}$	$\nu_2^{1/2}$	Total Samples	Good Samples	Ambient Dimension	Subspace Dimension	Corruption Factor
0.01	0.1	22	1	3584	$\approx 4$	20%

# ADMM Implementation I

$$\arg \min_{X, Z, \Pi} \underbrace{\lambda_r \|X\|_{\otimes, \alpha}}_{\text{low rank}} + \underbrace{\frac{1}{2} \|Z\Pi^{-1/2}\|_F^2}_{\text{weighted noise}} + \underbrace{\frac{D}{2} \log |\Pi|}_{\text{unk. variance}} \quad \text{s.t. } Y = X + Z$$

Form the augmented Lagrangian function with penalty parameter  $\mu$ :

$$\begin{aligned} \mathcal{L}_\mu(X, Z, \Lambda) &= \lambda_r \|X\|_{\otimes, \alpha} + \frac{1}{2} \|Z\Pi^{-1/2}\|_F^2 + \langle \Lambda, Y - X - Z \rangle + \frac{\mu}{2} \|Y - X - Z\|_F^2 \\ &\quad + \frac{D}{2} \log |\Pi| \end{aligned}$$

Solve for each primal and dual individually  $X, Z, \Lambda, \Pi$

# ADMM Implementation II

X update:

$$\begin{aligned} X_{k+1} &= \arg \min_{X_k} \mathcal{L}_\mu(X_k, Z_k, \Lambda_k) = \arg \min_{X_k} \lambda_r \|X_k\|_{\otimes, \alpha} + \frac{\mu}{2} \|Y - X_k - Z_k + \frac{1}{\mu} \Lambda_k\|_F^2 \\ &= \operatorname{prox}_{\lambda_r \mu^{-1} \|\cdot\|_{\otimes, \alpha}} \left( Y - Z_k + \frac{1}{\mu} \Lambda_k \right) = \mathbf{PSSV} \left( Y - Z_k + \frac{1}{\mu} \Lambda_k, \frac{\lambda_r}{\mu} \right) \end{aligned}$$

## PSSV - Notation

$$\mathbf{PSSV}(A, \tau, \alpha) = U_A (D_{A1} + \mathcal{S}_\tau[D_{A2}]) V_A^T$$

$$D_{A1} = \operatorname{diag}(\sigma_1(A), \dots, \sigma_\alpha(A), 0, \dots, 0)$$

$$D_{A2} = \operatorname{diag}(0, \dots, 0, \sigma_{\alpha+1}(A), \dots, \sigma_N(A))$$

$$\mathcal{S}_\tau[x] = \operatorname{sign}(x) \max(|x| - \tau, 0)$$

# ADMM Implementation III

Z update:

$$\begin{aligned} Z_{k+1} &= \arg \min_{Z_k} \mathcal{L}_\mu(X_k, Z_k, \Lambda_k) = \arg \min_{Z_k} \frac{1}{2} \|Z_k \Pi^{-1/2}\|_F^2 + \frac{\mu}{2} \|Y - X_k - Z_k + \frac{1}{\mu} \Lambda_k\|_F^2 \\ &= [\mu(Y - X_k) + \Lambda_k](\Pi^{-1} + \mu I)^{-1} \end{aligned}$$

$\Pi$  update:

$$\begin{aligned} \Pi_{k+1} &= \arg \min_{\Pi_k} \frac{1}{2} \|Z \Pi_k^{-1/2}\|_F^2 + \frac{D}{2} \log |\Pi_k| = \arg \min_{\Pi_k} \frac{1}{2} \text{tr}(Z^T Z \Pi_k^{-1}) + \frac{D}{2} \log |\Pi_k| \\ &\implies \nabla_{\Pi_k} f(\Pi_k) = \frac{-1}{2} (Z^T Z \odot \Pi_k^{-2}) + \frac{D}{2} \Pi_k^{-1} \\ &\implies \Pi_{k+1} = \frac{1}{D} Z^T Z \odot I = \frac{1}{D} (Y - X)^T (Y - X) \odot I \end{aligned}$$



# HPCA Convergence

From [7], convergence is shown under the following ADMM framework

$$\min_{x,y} f(x) + g(y) \quad \text{s.t.} \quad Ax + b = y$$

$$\text{W.L.O.G., HPCA} = \arg \min_{X,Z} \underbrace{\lambda_r \|X\|_{\otimes, \alpha}}_{f(X)} + \underbrace{\frac{1}{2} \|Z\Pi^{-1/2}\|_F^2}_{g(Z)} \quad \text{s.t.} \quad \underbrace{X}_{A=I} + Z = Y$$

1.  $f(X)$  : proper, lower semi-continuous, **semi-algebraic** function
  2.  $g(Z)$  : continuous differentiable, semi-algebraic function w/  $L_{\nabla g} > 0$
  3.  $\exists \gamma \in \mathbb{R}$  s.t.  $A^T A \succeq \gamma I$
  4.  $\{X_K, Z_k\}$  sequence generated by ADMM is bounded
- 1,2,3,4  $\implies$  convergence to KKT point (assuming aug. param.  $\mu > 2L_{\nabla g}$ )

# References

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- [2] R. Otazo, E. Candès, and D. K. Sodickson, “Low-rank plus sparse matrix decomposition for accelerated dynamic mri with separation of background and dynamic components,” *Magnetic Resonance in Medicine*, vol. 73, no. 3, pp. 1125–1136, 2015.
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- [6] T. Tong, C. Ma, and Y. Chi, *Accelerating ill-conditioned low-rank matrix estimation via scaled gradient descent*, 2020. DOI: 10.48550/ARXIV.2005.08898. [Online]. Available: <https://arxiv.org/abs/2005.08898>.

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- [7] K. Guo, D. Han, and T.-T. Wu, “Convergence of alternating direction method for minimizing sum of two nonconvex functions with linear constraints,” *International Journal of Computer Mathematics*, vol. 94, no. 8, pp. 1653–1669, 2017.